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The main topic of Chapter 11 is the design of control systems using state variable models. Full-state feedback design and observer design methods based on pole placement are discussed. Tests for controllability and observability are presented, and the concept of an internal model design is discussed.

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Professor Dorf is a Fellow of the IEEE and a Fellow of the ASEE. He is active in the fields of control system design and robotics.

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24. CHAPTER 2. E2.4. Mathematical Models of Systems. Since $R(s) = 1/s$ we have. $Y(s) = 6(s + 50) \cdot s(s +$

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30)(s + 10) The partial fraction expansion of Y (s) is given by $A_1 A_2 A_3 Y (s) = + + s s \dots$

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